

# Aeromagnetic Surveying with a Multi Rotor Unmanned Aircraft System

A Case Study of comparing Heli-Mag and UAV-Mag Data in Greenfield Exploration

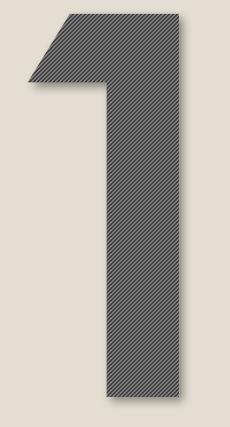
Telma Aisengart Jose Arce Carlos Cifuentes

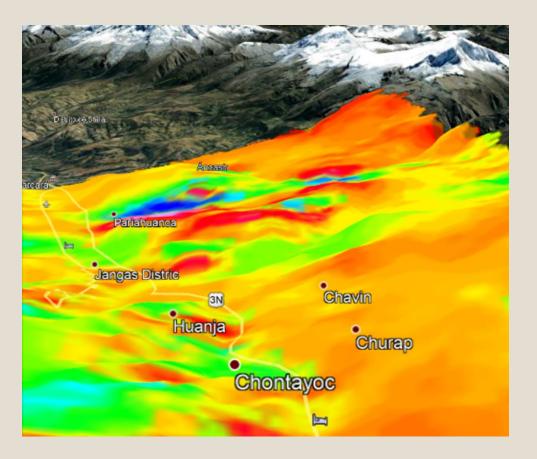
Date: October 8<sup>th</sup>, 2020

**Public Information** 

# Agenda

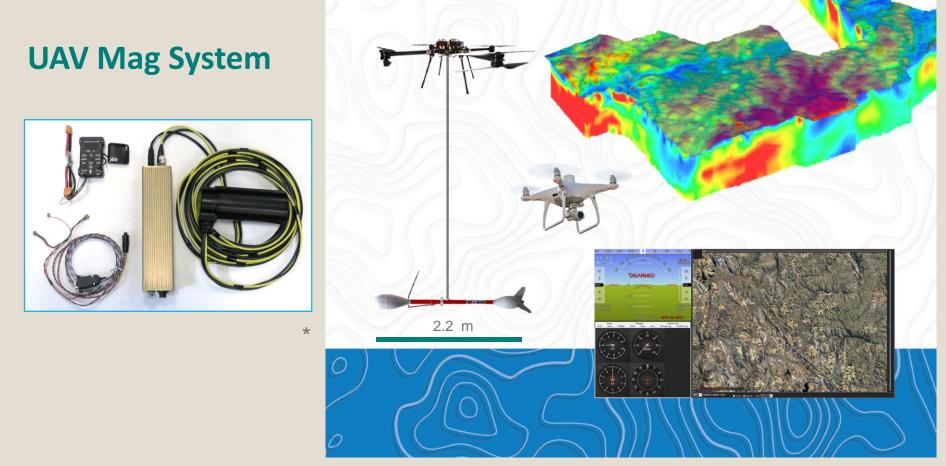
- 1. UAV Mag Surveys for Mineral Exploration
- 2. Magnetometers used for commercial Surveys
- 3. UAV Mag Surveys Field Data Acquisition, Quality Control and Processing
- 4. Tambo Sur UAV Mag and Helicopter data analysis
- 5. Conclusions





Within the past decade, the development of UAV Mag Systems has been possible due to the following:

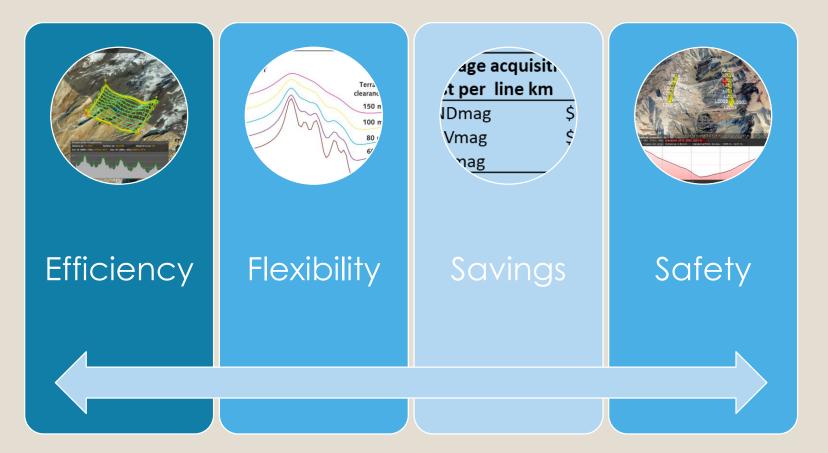
- Cost effective commercially available UAV platforms
- Development of low weight Magnetic sensors
- Software development for UAV flight path planning and data processing



\* Source: https://www.gemsys.ca/uav-magnetometers/

\*\* Source: http://www.geofisicos.com/es/servicio/prospeccion-mineral/magnetometria-en-uav

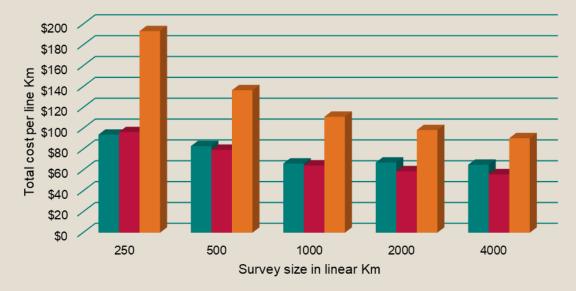
# UAV Mag Surveys for Mineral Exploration UAV Mag Advantages

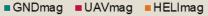


### **UAV Mag advantages**

- The mobilization and logistics is less complicated and less expensive than other aerial systems
- It is more cost-effective and requires fewer maintenance and operation personnel, compared to conventional airborne geophysical platforms (fixed wing or helicopters)

#### Mag Surveys – Total cost per line Km Mobilization - Data Aquisition - Processing

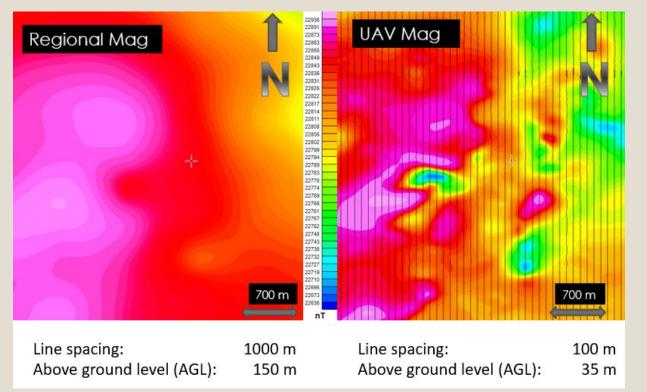




Average mobi			
cost to Chiles II – Región			
GNDmag	\$3,000		
UAVmag	\$5 <i>,</i> 000		
Helimag	\$18,000		

Average acquisition		
cost per line km		
GNDmag	\$60	
UAVmag	\$50	
Helimag	\$80	

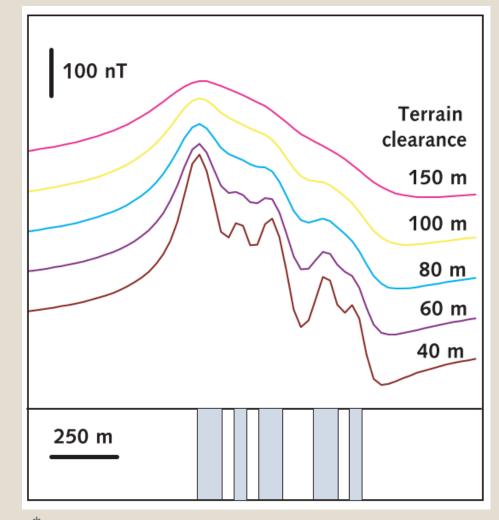
### **UAV Mag advantages**



- In steep topography the UAV systems are capable to fly closer to the surface, compared to the helicopter or fixed-wing platforms
- Increasing flight height and line spacing greatly reduces the resolution of magnetic survey

### **UAV Mag advantages**

- The magnetic signal is inversely proportional to the square of the distance from the source.
- In this case a Magnetic Survey flown at 150m AGL would be able to register the sum of the individual anomalies. A UAV Mag Survey flown at 40 m is capable to register the individual response of the anomalies.





#### There are two basic types of magnetometer measurement:

#### **Fluxgate magnetometers**

- Measure the vector components of a magnetic field. Typically the fluxgate are used for airborne flight orientation instead of magnetic field surveying
- Resolution of 0.1 nT
- The directional effect is very high
- Thermal drift of 0.6 nT / C and Offset when it is turned on and off of 50 nT
- They are extremely sensitive to very minor variations in sensor tilt

#### **Total field magnetometers**

- Measure the magnitude of the vector magnetic field. The total field magnetometers more commonly used are Proton Precession, Potassium, Cesium and Overhauser
- Resolution of 0.001 nT
- The directional effect is very low
- No temperature drift
- Standard magnetometers for commercial Mag Surveys

### There are two basic types of magnetometer measurement:

Fluxgate magnetometers



**Total field magnetometers** 



### **Technical Specifications and Mag Sensors available in the market**

**Industry standard for Mag Airborne Surveys** 

Mag S	ensor	<b>Technical</b>	Specifica	tions
may J	CIISUI	recimical	Specifica	

Sensitivity	0.01 nT	]
Absolute Accuracy	±10 nT	
Noise Envelope	0.10 nT	
Ambient Range	20,000 to 100,000 nT	
Sampling Interval	0.1 second	
Heading Effect	< 2.0 nT	

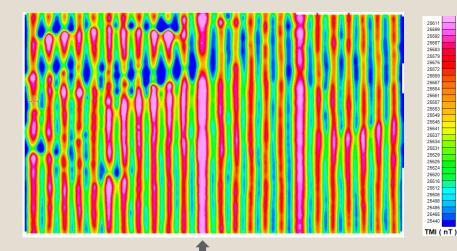
\*

Company	Airborne Mag	UAV Mag
GEM	GMP-35A Potassium Magnetometer	Airbird GMP-35U Potassium Magnetometer
A DIVISION OF LRS	CB-3 Cs Magnetometer Sensor	CS-VL Cesium Magnetometer
	G-823A Cesium Magnetometer	MagArrow Laser Pumped Cesium Vapor

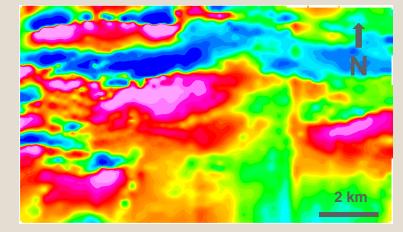
\* Source: Geological Survey of Canada aeromagnetic surveys: design, quality assurance, and data dissemination, M. Coyle, R. Dumont, P. Keating, F. Kiss, and W. Miles, 2014

### Raw data from an airborne mag survey

Fluxgate magnetometer



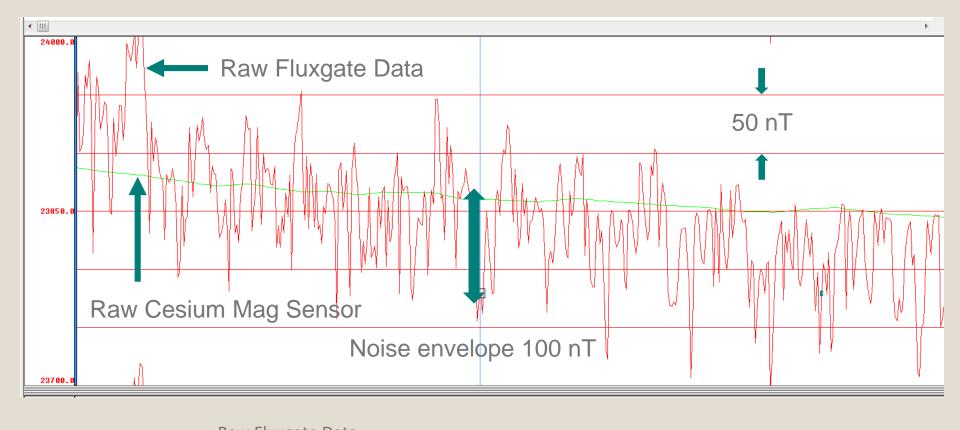
#### **Total field magnetometer**



Directional effect of the Fluxgate magnetometer (stripes on the raw data)

Fix wing survey Line spacing 250m Flight Altitude 100 m

### Raw data from airborne mag survey



Raw Fluxgate Data
Raw Cesium Mag Sensor



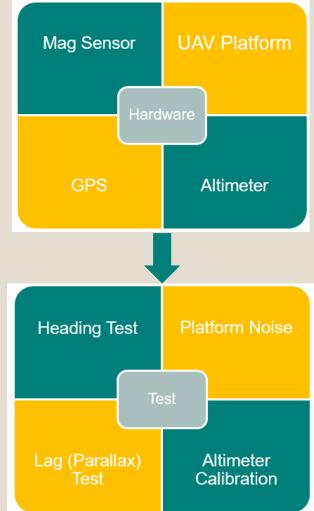
**Equipment used in Data Acquisition** 





### **Quality Control of Aeromagnetic Surveys**

- Inspection of airborne platform, geophysical equipment and personnel experience
- Airborne platform tests and calibrations
- Inspection of data compliance
  - Data integrity, noise and gaps
  - Flight path deviation
  - Flight line spacing
- Data processing procedures

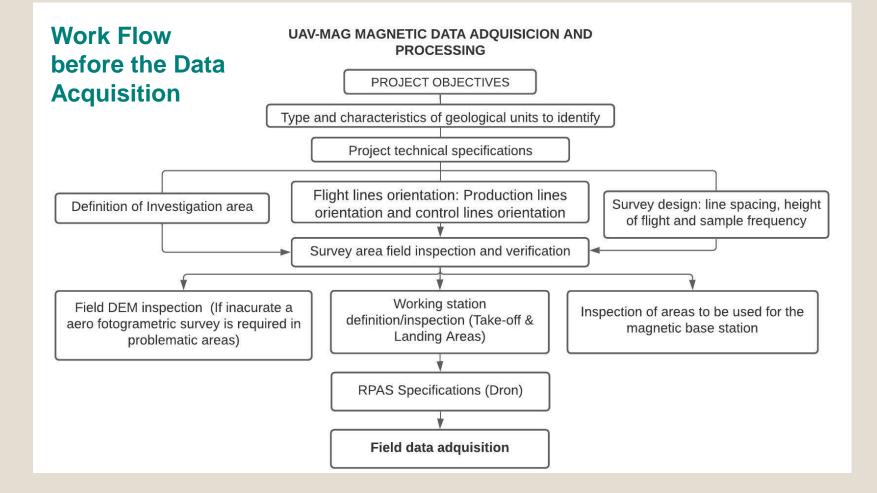


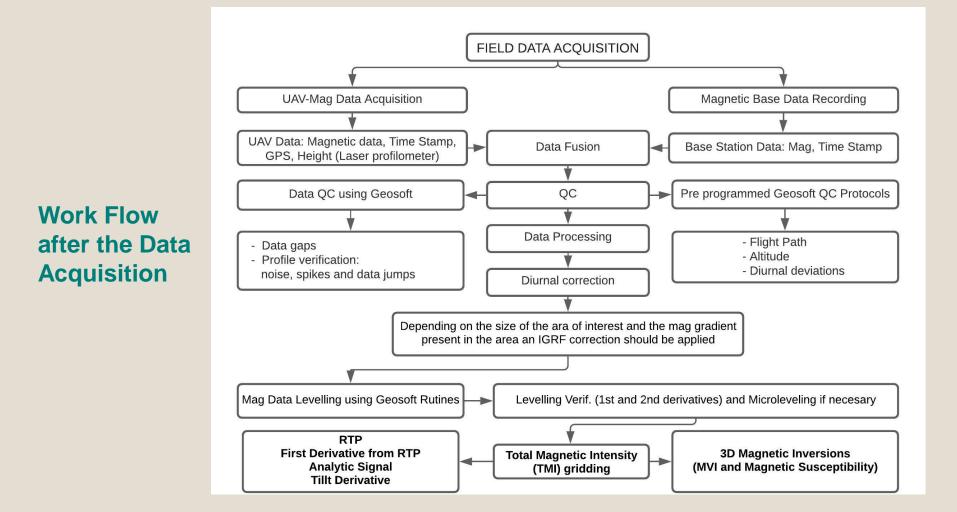
\* Source: Geological Survey of Canada aeromagnetic surveys: design, quality assurance, and data dissemination, M. Coyle, R. Dumont, P. Keating, F. Kiss, and W. Miles, 2014

### **Examples of Calibrations**

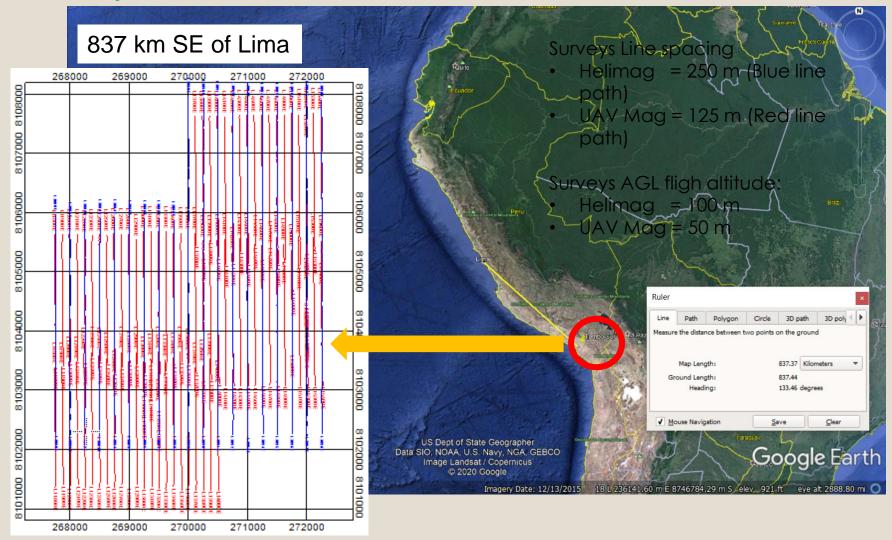
The Heading Test is designed to demonstrate that the flight platform and the data acquisition system do not have a significant heading effect, that is, that the same magnetic field value will be recorded at the same location, regardless of the heading in which the waypoint is flown.



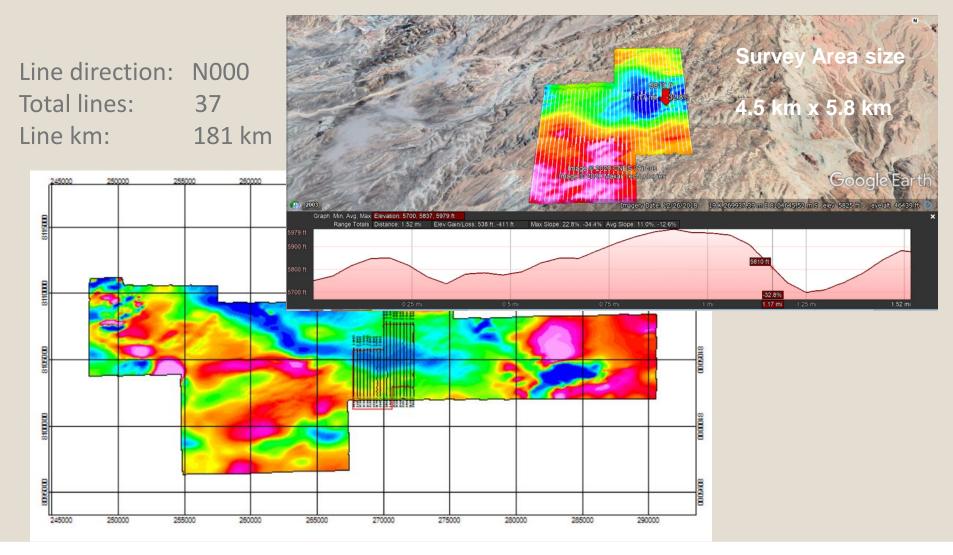




#### **Survey Location**



### **UAV Magnetic Survey Specifications**



### **Survey Equipment**

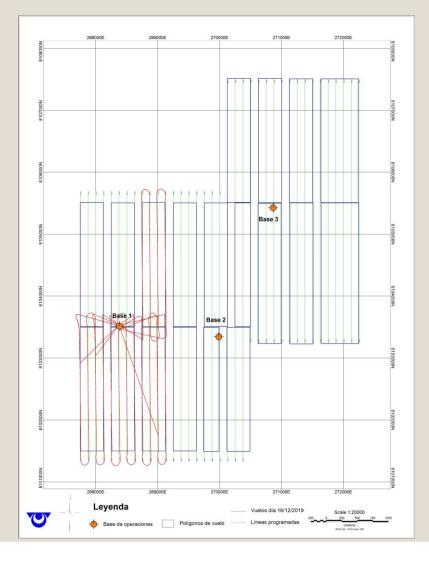
UAV Platform: BFD Systems HSE8Number of motors: 8Batteries: 4 of 22000 mA/h each





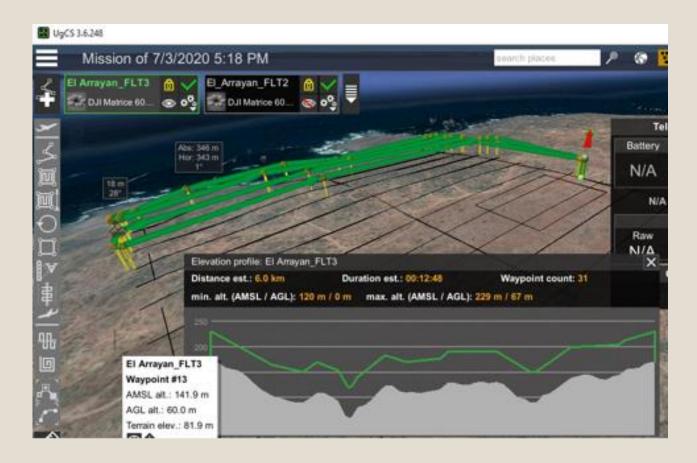
Mag system:GEM AirbirdSensor:Potassium GSMP-35UResolution:0.0001 nTAbsolute Accuracy:+/- 0.1 nTHeading Error:+ / - 0.05 nT

### **Data Acquisition**



- In total three take-off/landing sites were used to cover the entire area
- The location of take-off/landing sites and the daily flight plan were programmed considering the topography, autonomy of the UAV, wind conditions and ferry time
- In normal conditions the UAV BFD model SE-8 has a flight autonomy of 25 minutes, however due to the complex topography and wind conditions during the present survey the flight time was reduced to a maximum to 16 minutes

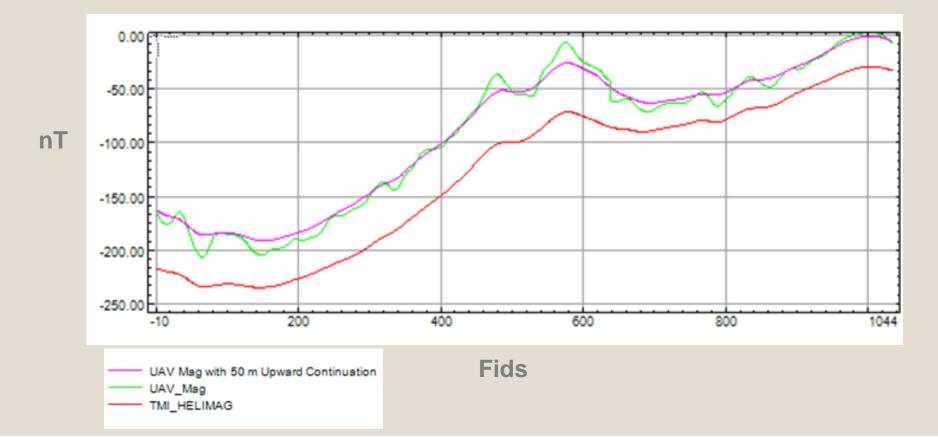
### **UgCS UAV Mission Planner**



- The UAV Flight Plan software uses a DEM to plan the surface flight path
- It is recommend to use a high resolution DEM to plan an appropriate drape surface to avoid UAV collisions with the ground

### Line Data

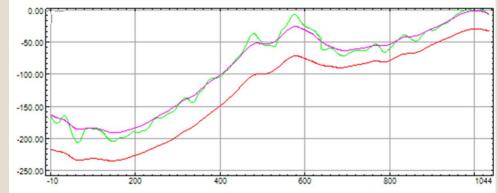
Direct Line Data Comparison between Helimag Data (L3082 – Red), UAV Mag Data (L12200 – Geen) and Upward continued 50m UAV Mag Data (L12200 – Magenta)



### Line Data

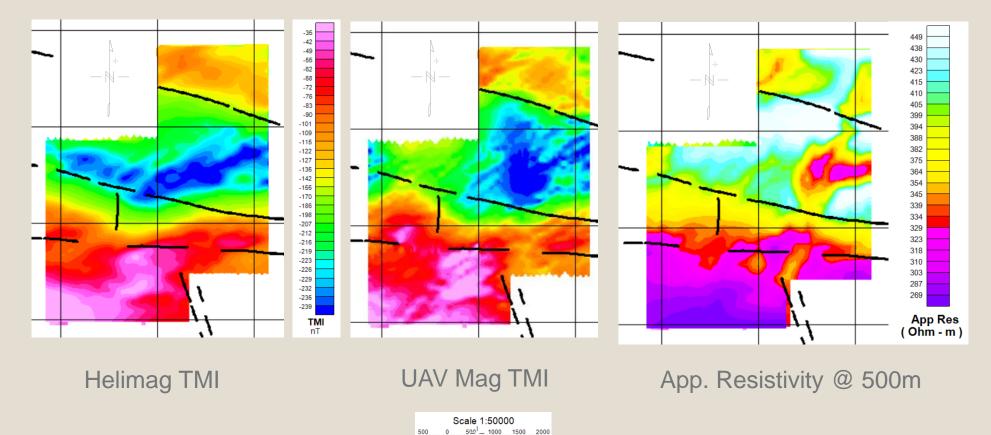
- The Mag UAV on line data presents the same magnetic trend and response as the on line Helimag data
- The Mag UAV lines registered a more detailed magnetic response due to the flight height
- The details of anomalies ranging from 30m to 100m in amplitude observed in the UAV Mag survey cannot be observed in the Helimag data
- The 50m upward continued UAV Mag data have a good correlation with the Helimag data

Direct Line Data Comparison between Helimag Data (L3082 – Red), UAV Mag Data (L12200 – Geen) and Upward continued 50m UAV Mag Data (L12200 – Magenta)



### **Grid Data**

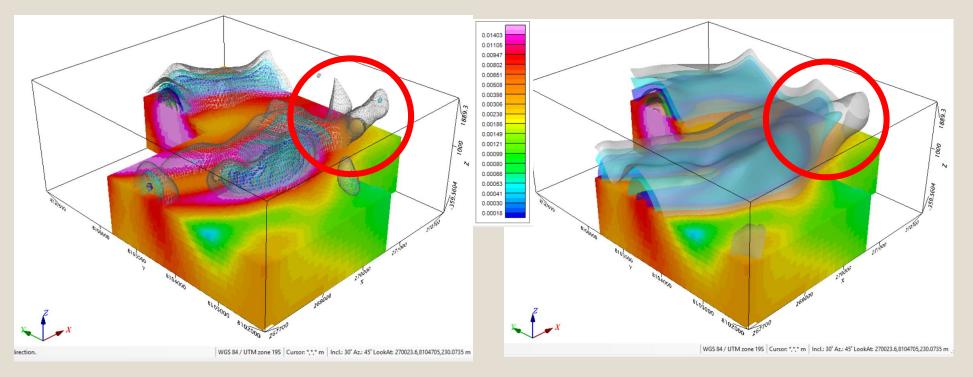
Helimag Grid at 250 m line spacing and 100 m AGL, UAV Mag Grid at 125m line spacing and 50 m AGL and App. Resistivity @ 500m from a ZTEM survey



(meters) WGS 84 / UTM zone 195

### **3D MVI Data**

N045 View with inclination 30 of the Heli Mag Amplitude Magnetization Voxel and isosurfaces of the Heli Mag and UAV Mag MVI invertions

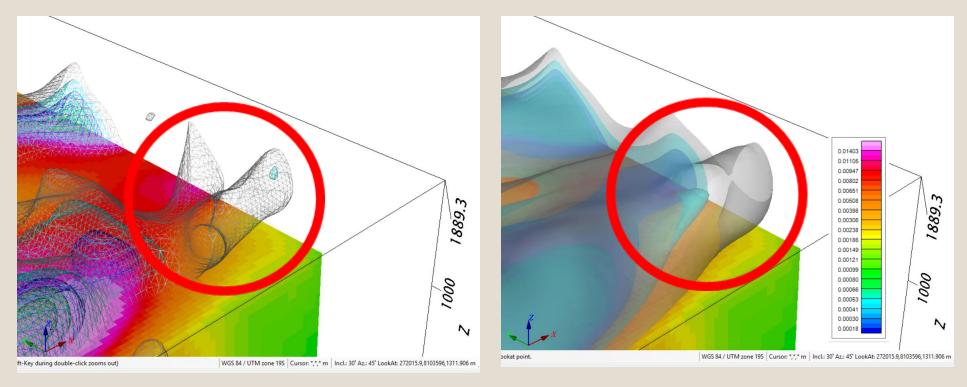


Heli Mag 3D MVI Data

UAV Mag 3D MVI Data

### **3D MVI Data**

N045 View with inclination 30 of the Heli Mag Amplitude Magnetization Voxel and isosurfaces of the Heli Mag and UAV Mag MVI invertions



UAV Mag 3D MVI Data

Heli Mag 3D MVI Data



# Conclusions

## Conclusion

- Within the past decade, the development of UAV platforms and magnetic sensors has permitted to integrate UAV aeromagnetic platforms that can register magnetic data with similar characteristics to Airborne Mag Surveys
- For Mining Exploration a UAV Mag System should comply with similar technical specifications required in standard aeromagnetic platforms
- The UAV Mag Surveys have the advantage to have a lower total cost compared with Heli Mag Surveys and is competitive with Ground Mag Surveys.
- The UAV Mag Systems can fly close to the ground, specially in rough terrain, permitting a closer line spacing in order to obtain High Resolution Magnetic Surveys.

## Conclusion

- The limitations of the UAV Mag Systems are the short time of the batteries, high survey altitude, the road access and the high wind gusts
- The line to line comparison shows that both data sets registered the same magnetic trend
- The UAV Mag data registered a higher resolution and more detailed magnetic response.
- The MVI inversion of the UAV Mag data shows higher resolution and more details
- The UAV Mag Test Survey flown in a Greenfield Exploration Environment demonstrated that the UAV Mag platform can be used to do High Resolution Magnetic Surveys

### References

- Airborne Geophysics: Old Methods New Images, Reeves, C.V., Reford, S.W. and Milligan, P.R., 1997
- Geological Survey of Canada aeromagnetic surveys: design, quality assurance, and data dissemination, M. Coyle, R. Dumont, P. Keating, F. Kiss, and W. Miles, 2014
- https://www.gemsys.ca/uav-magnetometers/
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- https://scintrexltd.com/product-category/airborne/
- http://www.geofisicos.com/es/servicio/prospeccion-mineral/magnetometriaen-uav



# Thanks ....

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